2-channel speed sensor

Sensor with current output or voltage output (standstill voltage)

GEL 2475

Technical information Version 06-29-2021

Description

- Application-proven speed sensor using magnetic scanning
- Maintenance- and wear-free operation by contactless rotary motion measuring
- Wide measuring range for reliable detection of creeping without pulse loss and also for fast rotary motion
- Detection of direction by evaluating two channels with 90° phase offset
- Constant duty cycle of output signals



- Target wheel module: 1.00 to 3.50
- Degree of protection: IP X8 sensor housing
- in accordance with DIN EN 50155:2018-05

Advantages

- Current output signals insensitive to electro-magnetic interference fields
- Cable break monitoring via current output or voltage output with standstill voltage
- Easy to install due to large measuring distance

Field of application

- Rail vehicle industry
 - Traction monitoring
 - Anti-slip protection
 - Motor speed
 - Anti-skid protection
 - Automatic train protection
 - Odometry

Do you have special requirements regarding flange shape, shaft length, number of channels, cable protection, cable outlet, connector assembly or EMC concept?

Then talk to us. Our experts can design the optimal solution for your application from an extensive modular system and will be pleased to advise you how to customize your solution in the most cost-efficient way.

Write to support@lenord.de or call +49 208 9963-215.





-51T-2475

Voltage output Technical data

Signal pattern	E-	S-	V-	X-	D-	H-	
Electrical data							
Supply voltage U _B (reverse polarity protected)	10 to 30 V D0	C					
Current consumption I _B (without load)	≤ 30 mA						
Output signal (short-circuit-proof)	Square-wave	signals					
Output signal level High ⁽¹⁾	≥ U _B - 1.5 V						
Output signal level Low ⁽¹⁾	≤ 1.0 V						
Output current per channel	≤ 20 mA						
Frequency range	0 to 20 kHz						
Duty cycle	50 % ± 10 %	(2)					
Phase offset	_		typ. 90°				
Mechanical data			<u> </u>				
Sensor tube material	Stainless stee	el					
Flange material	Stainless stee	el					
Sensor weight (incl. 2 m cable)	500 g	500 g					
Cable							
Connection	Cable outlet straight or at side, connector in accordance with specification						
Cable length	≤ 100 m						
Screening note	Cable screen	is connecte	d directly or, as	an option, ca	pacitively in th	e sensor	
Environmental testing							
Working and operating temperature	-40 °C to +12	0 °C					
Storage temperature	-40 °C to +12	:0 °C					
Dielectric strength	500 V AC/750	0 V DC (DIN	EN 50155:201	8-05)			
Electromagnetic compatibility ⁽³⁾	DIN EN 5012	1-3-2:2017-	11				
Degree of protection on measuring side ⁽⁴⁾	IP X8						
Vibration resistance	DIN EN 6137	3:2011-04 ca	at. 3				
Shock resistance	DIN EN 6137	3-2011-04 c	at. 3				
MTTF value	2,000,000 h a	at 55 °C					
Requirements for the target whee							
Material	Ferromagnet	ic steel					
Tooth form	Involute gear	teeth as per	DIN 867 (other	rs upon reque	est)		
Width	≥ 10 mm (smaller upon request)						
Module m	1.00/1.25/1.5	1.00/1.25/1.50/1.75/2.00/2.25/2.50/3.00/3.25/3.50					
Air gap	see air gan ta	ee air gap table, page 12					

⁽¹⁾ depending on output current and temperature

⁽²⁾ applies to operation with nominal air gap and toothing as per DIN 867

⁽³⁾ Observe EMC notes in the mounting/operating instructions

⁽⁴⁾ Degree of protection on the cable outlet side depends on cable gland or cable protection

Signal patterns E-, S- and V-

Cable data				
Cable	halogen-free and screened (1)			
Cable diameter	5.4 ± 0.2 mm			
Cable cross section	$4 \times 0.5 \text{ mm}^2$			
Minimum bending radius static/dynamic	16 mm / 27 mm			

Signal pattern X-

Cable data				
Cable	halogen-free and screened (1)			
Cable diameter	6.5 ± 0.3 mm			
Cable cross section	6 × 0.5 mm ²			
Minimum bending radius static/dynamic	20 mm / 33 mm			

Signal patterns D- and H-

Cable data				
Cable	halogen-free, screened (1)			
Cable diameter	8.0 ± 0.3 mm			
Cable cross section	12 × 0.34 mm ²			
Minimum bending radius static/dynamic	24 mm / 40 mm			

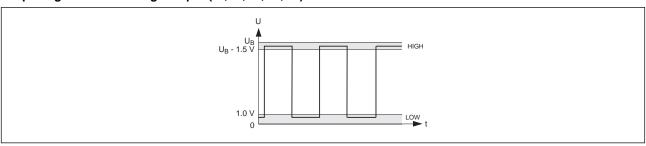
⁽¹⁾ Specification upon request

Voltage output Output signals and connection

Signal pattern for voltage output

	Output signals	Supply voltage	Pulse diagram
E-	1 channel	10 to 30 V DC	
S-	1 channel with directional signal forward backward	10 to 30 V DC	
V-	2 channels, 90° phase offset	10 to 30 V DC	
X-	2 channels, 90° phase offset, with inverse channels	10 to 30 V DC	
D-	2 channels, electrically isolated, 90° phase offset	10 to 30 V DC	
Н-	2 channels, electrically isolated, 90° phase offset, with inverse channels	10 to 30 V DC	

Output signal level – voltage output (S-, V-, X-, D-, H-)



Pin assignment – voltage output (E-, S-, V-, X-, D-, H)

Signal	E-	S-	V-	X-	D-		H-	
Channel 1	YE	YE	YE	YE	YE		YE	
Channel 2		WH	WH	WH		WH		WH
Channel 1 inverse				BK			BK	
Channel 2 inverse				BN				BN
GND (0 V)	BU	BU	BU	BU	BU	GY	BU	GY
+U _B	RD	RD	RD	RD	RD	PK	RD	PK
Cables/Screens	1/1	1/1	1/1	1/1	1/1		1,	/ 1

Cable screen is connected directly or, as an option, capacitively in the sensor

Core identifier: BK black, BN brown, BU blue, GY gray, PK pink, RD red, WH white, YE yellow

Voltage output with standstill voltage Technical data

	DM	EM		
Electrical data				
Supply voltage U _B (reverse polarity protected)	10 to 20 V DC			
Current consumption I _B (without load)	≤ 12 mA per channel	[
Output signal (short-circuit-proof)	Square-wave signals			
Output signal level High ⁽¹⁾	≥ U _B - 1.8 V			
Output signal level Low ⁽¹⁾	≤ 1.5 V			
Output current per channel	≤ 10 mA			
Frequency range	0 to 8 kHz			
Duty cycle	50 % ± 10 % ⁽²⁾			
Phase offset	typ. 90°	_		
Mechanical data	71			
Sensor tube material	Stainless steel			
Flange material	Stainless steel			
Sensor weight	500 g			
(incl. 2 m cable)	3			
Cable				
Cable	halogen-free and scr	eened ⁽³⁾		
Cable diameter	8.0 ± 0.3 mm	5.4 ± 0.2 mm		
Cable cross section	12 x 0.34 mm ²	4 x 0.5 mm ²		
Minimum bending radius static/dynamic	24 mm/40 mm	16 mm/27 mm		
Screening note	Cable screen is conr tion, capacitively in the	nected directly or, as an op- ne sensor		
Environmental testing				
Working and operating temperature	-40 °C to +85 °C			
Storage temperature	-40 °C to +120 °C			
Dielectric strength	500 V AC/750 V DC	(DIN EN 50155:2018-05)		
Electromagnetic compatibility ⁽⁴⁾	DIN EN 50121-3-2:2	017-11		
Degree of protection on measuring side ⁽⁵⁾	IP X8			
Vibration resistance	DIN EN 61373:2011-	04 cat. 3		
Shock resistance	DIN EN 61373-2011-	-04 cat. 3		
MTTF value	2,000,000 h at 55 °C			
Requirements for the target wheel	'			
Material	Ferromagnetic steel			
Tooth form	Involute gear teeth a request)	Involute gear teeth as per DIN 867 (others upon		
Width		≥ 10 mm (smaller upon request)		
Module m	, ,	1.00/1.25/1.50/1.75/2.00/2.25/2.50/3.00/3.25/3.50		
Air gap	see air gap table, pa	ge 12		

⁽¹⁾ depending on output current and temperature

⁽²⁾ applies to operation with nominal air gap and toothing as per DIN 867

⁽³⁾ Specification upon request

⁽⁴⁾ Observe EMC notes in the mounting/operating instructions

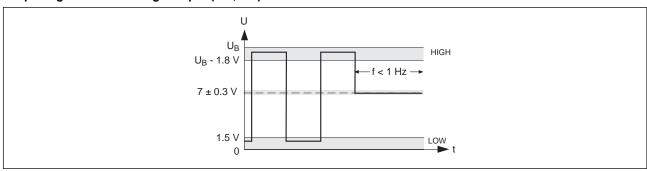
 $^{^{(5)}}$ Degree of protection on the cable outlet side depends on cable gland or cable protection

Output with standstill voltage – output signals and connection

Signal pattern with standstill voltage (DM, EM)

Outp	out signals	Supply voltage	Pulse diagram	
DM	2 channels, electrically isolated, 90° phase offset, with standstill voltage	2 × 10 to 20 V DC	7V <1 Hz 7V <1 Hz	
EM	1 channel	10 to 20 V DC		

Output signal level - voltage output (DM, EM)



Pin assignment – voltage output (DM, EM)

Signal		DM				
Channel 1	YE		YE			
Channel 2		WH				
GND (0 V)	BU	GY	BU			
+U _B	RD	PK	RD			
Cables/Screens		1/1 1/1				
Cable screen is connected directly or, as an option, capacitively in the sensor						

Current output Technical data

	DI	VI	EI				
Electrical data							
Supply voltage U _B (reverse polarity protected)	Supply voltage U _B (reverse polarity protected) 10 to 20 V DC						
Output signal (short-circuit-proof)	Square-wave signals						
Output signal level High ⁽¹⁾	typ. 14 mA	<u> </u>					
Output signal level Low ⁽¹⁾	typ. 6 mA						
Output current per channel	≤ 16 mA						
Frequency range	0 to 12 kHz						
Duty cycle	50 % ± 10 % ⁽²⁾						
Phase offset	typ. 90°		-				
Mechanical data	- 1		1				
Sensor tube material	Stainless steel						
Flange material	Stainless steel						
Sensor weight	500 g						
(incl. 2 m cable)							
Cable							
Cable	halogen-free and sci	reened ⁽³⁾					
Cable diameter	$5.4 \pm 0.2 \text{ mm}$						
Cable cross section	4 x 0.5 mm ²						
Minimum bending radius static/dynamic	16 mm/27 mm						
Screening note	Cable screen is connected directly or, as an option, capacitively in the sensor						
Environmental testing							
Working and operating temperature	-40 °C to +120 °C						
Storage temperature	-40 °C to +120 °C						
Dielectric strength	500 V AC/750 V DC	(DIN EN 50155:2018	3-05)				
Electromagnetic compatibility ⁽⁴⁾	DIN EN 50121-3-2:2	017-11					
Degree of protection on measuring side ⁽⁵⁾	IP X8						
Vibration resistance	DIN EN 61373:2011-	-04 cat. 3					
Shock resistance	DIN EN 61373-2011-04 cat. 3						
MTTF value	2,000,000 h at 55 °C						
Requirements for the target wheel							
Material	Ferromagnetic steel						
Tooth form	Involute gear teeth as per DIN 867 (others upon request)						
Width	≥ 10 mm (smaller upon request)						
Module m	1.00/1.25/1.50/1.75/2.00/2.25/2.50/3.00/3.25/3.50						
Air gap	see air gap table, page 12						

depending on output current and temperature
(2) applies to operation with nominal air gap and toothing as per DIN 867

⁽³⁾ Specification upon request

⁽⁴⁾ Observe EMC notes in the mounting/operating instructions

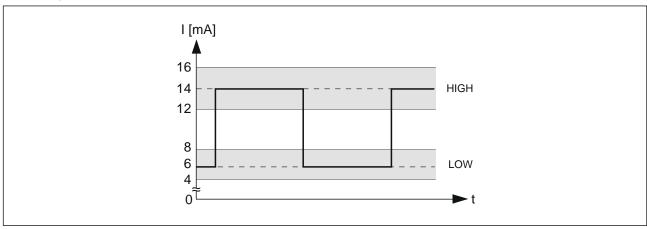
⁽⁵⁾ Degree of protection on the cable outlet side depends on cable gland or cable protection

Current output Technical data

Signal pattern

	Output signals	Supply voltage	Pulse diagram
EI	1 channel	10 to 20 V DC	
VI	2 channels, 90° phase offset	10 to 20 V DC	
DI	2 channels, electrically isolated, 90° phase offset	2 x 10 to 20 V DC	

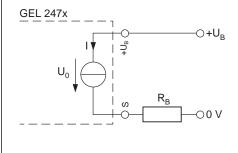
Output signal level



Core assignment

Signal	VI	EI	DI	
Channel 1	blue	blue	blue	
Channel 2	green			green
+U _B	red	red	red	yellow
Cables/Screens	1/1		1/1	

Cable screen is connected directly or, as an option, capacitively in the sensor



U_B Operating voltageS Signal

Measuring resistor

The measuring resistor $R_{\rm B}$ to be connected at the current output must not exceed or fall below a certain value. The following relation applies:

$$R_{B, max} = (U_B - 5 \text{ V})/I_{max}$$

with
$$U_B = 10$$
 to 30 V DC and $I_{max} = 16$ mA

Example for $U_B = 15 \text{ V}$:

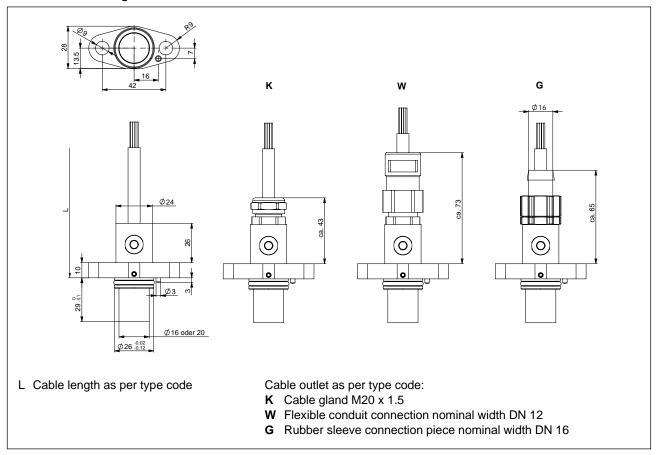
 $R_{B, \text{max}} = 10 \text{ V/16 mA} = 625 \Omega$

 $R_{B, min} = 240 \Omega$

Technical drawings

All dimensions in mm, general tolerance DIN ISO 2768 mK

Dimensional drawing

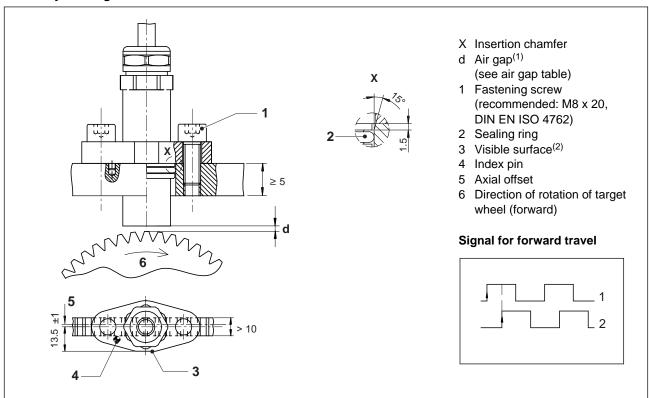


Cable screen is connected directly or, as an option, capacitively in the sensor Observe EMC notes in the mounting instructions.

Technical drawings

All dimensions in mm, general tolerance DIN ISO 2768 mK

Assembly drawing



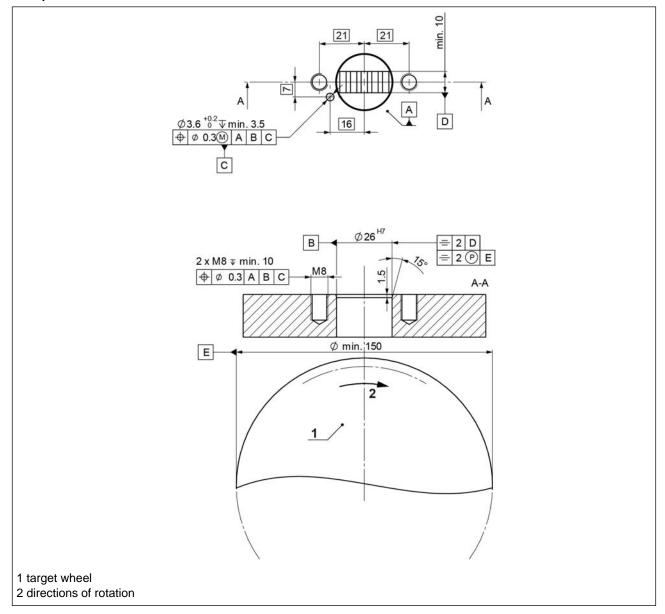
⁽¹⁾ depending on signal pattern and module

⁽²⁾ Looking at the visible surface, the signals are output forward when the target wheel rotates clockwise.

Technical drawings

All dimensions in mm, general tolerance DIN ISO 2768 mK

Hole pattern

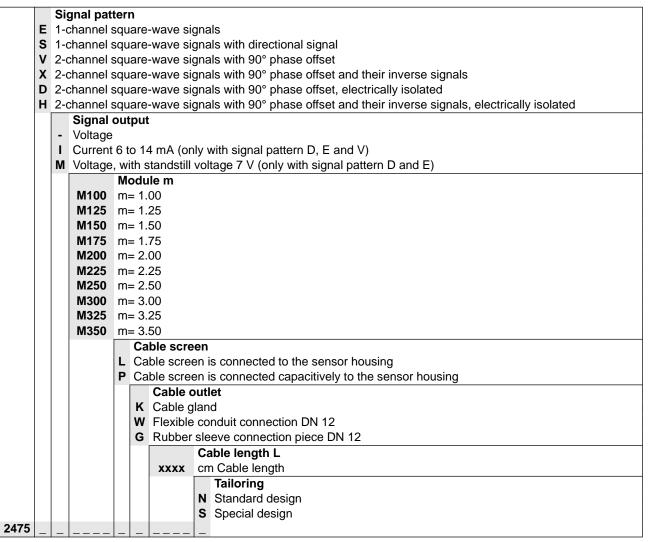


Air gap table

Air gap table

Module	Permissible air gap	Nominal air gap	max. permissible radial runout			
1.00	0.2 to 1.4 mm	0.5 mm				
1,.25	0.2 to 1.4 mm	0.5 11111				
1.50	0.2 to 1.8 mm	0.7 mm				
1.75	0.2 to 1.6 min	0.7 111111				
2.00	0.2 to 2.2 mm					
2.25	0.2 to 2.2 mm		± 0.3 mm			
2.50						
2.75	0.2 to 2.8 mm	0.7 mm				
3.00	0.2 to 2.0 111111					
3.25						
3.50	0.2 to 3.0 mm					

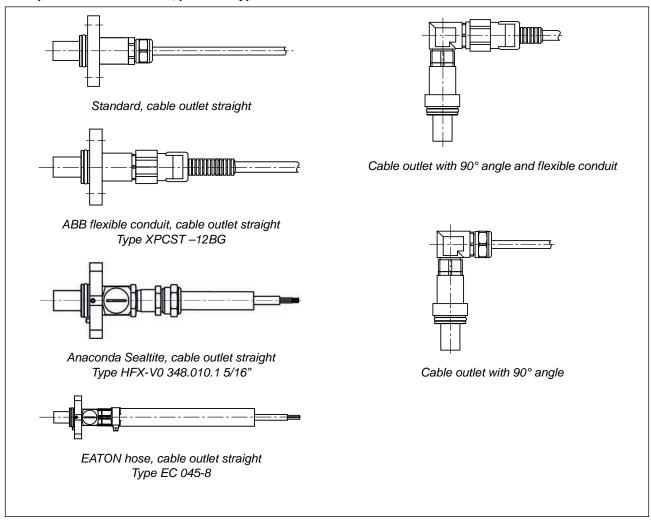
Type code GEL 2475



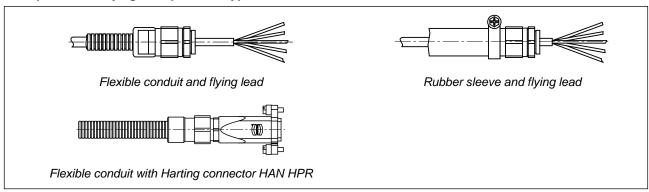
Note: A Y-number is assigned for a customer-specific special version. A special design GEL 2475Yxxx is manufactured according to drawing or application description.

We can manufacture according to your specifications:

Examples for the sensor side, preferred types

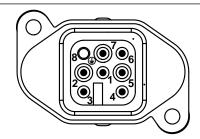


Examples for the flying lead, preferred types



Examples

Pin assignment Harting connector HAN HPR, preferred type



Pin	E-	V-	X-	D-	S-	EI	DI	VI	EM	DM	VM
1	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}	+U _{B1}
2	GND1	GND1	GND1	GND1	GND1	Channel 1	Channel 1	Channel 1	GND1	GND1	GND1
3	Channel 1	Channel 1	Channel 1	Channel 1	Channel 1	-	-	-	Channel 1	Channel 1	Channel 1
4	-	Channel 2	Channel 2	Channel 2	Channel 2	ı	1	1	1	Channel 2	Channel 2
5	-	-	Channel 1 inverse	GND2	ı	ı	Channel 2	Channel 2	-	GND2	-
6	-	-	Channel 2 inverse	-	-	-	-	-	-	-	-
7	-	-	-	+U _{B2}	-	-	+U _{B2}	-	-	+U _{B2}	-
8	Screen	Screen	Screen	Screen	Screen	Screen	Screen	Screen	Screen	Screen	Screen

If you decide to have our speed sensors assembled with cable protection and connectors, we recommend using the preferred types shown in the figure. The required materials are field-tested in large quantities and are always in stock. This guarantees the fastest delivery times with the best material availability and the lowest prices due to large purchasing volumes.

If you need help in finding the product you need, please contact our internal sales team at support@lenord.de or call +49 208 9963-215.



Lenord, Bauer & Co. GmbH Dohlenstraße 32 46145 Oberhausen, Germany Phone: +49 208 9963–0

Fax: +49 208 676292 Internet: www.lenord.com E-Mail: info@lenord.de

Right to technical changes and errors reserved.