



**Masterspeed**

( MTS )

**DC SERVO  
AMPLIFIERS**



P. N. : D.S. / 18.05.16 / MTS / 04

MODEL	MTS 60						MTS 140						MTS 200					
SIZE (A)	4/8	8/16	10/20	14/28	20/40	25/50	4/8	8/16	10/20	14/28	20/40	25/50	4/8	8/16	10/20	14/28	20/40	25/50
Nominal Current (Arms)	4	8	10	14	20	25	4	8	10	14	20	25	4	8	10	14	20	25
Peak Current (Arms) x 2 sec.	8	16	20	28	40*	50*	8	16	20	28	40*	50*	8	16	20	28	40*	50*
FDC: Supply Line Fuse (T-type = time-lag)	4 A 250V	8 A 250V	10 A 250V	14 A 250V	20 A 250V	25 A 250V	4 A 250V	8 A 250V	10 A 250V	14 A 250V	20 A 250V	25 A 250V	4 A 250V	8 A 250V	10 A 250V	14 A 250V	20 A 250V	25 A 250V
Supply (3PH)	44 VAC <sup>1</sup>						95 VAC <sup>1</sup>						145 VAC <sup>1</sup>					

<sup>1</sup> : Recommended DC power supply \* : Peak current = x 1 second

### STANDARD FEATURES

- ⇒ Driving motor range up to 15 Nm (2142.8 oz.-in.)
- ⇒ Internal power supply and dumping circuit
- ⇒ Built-in cooling fan when required
- ⇒ Surface Mount Technology
- ⇒ Five LED (Red/Green) indicating operating status
- ⇒ Five calibration potentiometers
- ⇒ IGBT or POWER MOSFET bridge
- ⇒ Removable power module
- ⇒ Completely protected from:
  - over/under supply voltage
  - over temperature
  - external short circuit motor polarity
  - faulty or inverted tachometer
- ⇒ **RD** Differential reference control mode
- ⇒ **TO** Tachogenerator feedback

### SPECIFICATIONS

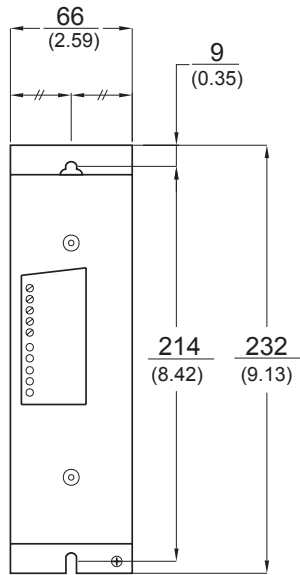
- ⇒ Supply voltage range:
  - (MTS 60) = 22 - 44 Vdc
  - (MTS 140) = 30 - 95 Vdc
  - (MTS 200) = 45 - 145 Vdc
- ⇒ Output voltage:..... 1.35x VAC supply
- ⇒ Input reference (differential):..... ± 10Vdc
- ⇒ Input-output demand current:..... ± 10Vdc
- ⇒ Output voltage for ext. use:..... +10 / -10Vdc @ 3.5mA
- ⇒ Enable signals:..... +10 - 30Vdc
- ⇒ PWM frequency:..... 20 KHz
- ⇒ Motor current monitor:..... ±7,5V (At peak current)
- ⇒ Operating temperature:..... 0 - 40 °C ( 32 - 104 °F )
- ⇒ Humidity(without condensation):..... 10 - 95%

### OPTIONS

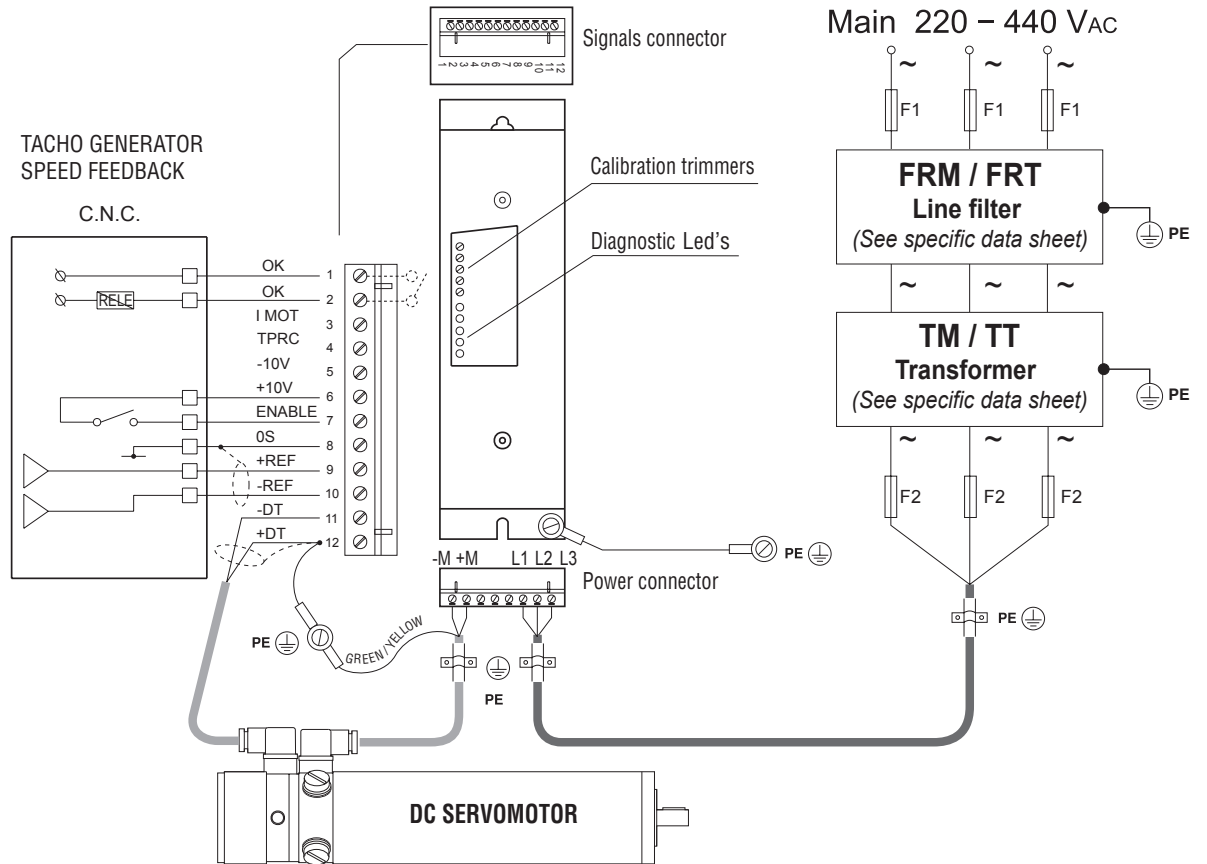
- ⇒ **AO** Armature Feedback
- ⇒ **EO** Encoder Feedback
- ⇒ **IO** Demand current (torque mode)
- ⇒ **PD** PWM + Direct



Dimensions in  $\frac{mm}{(inches)}$



Weight: 2.7 Kg



**MTS - 200 - 10 / 20 - RX - S - 1000 / T0 - RD**

**DRIVE LINE**

**POWER SUPPLY:** 060 = 60 Vdc  
140 = 140 Vdc  
200 = 200 Vdc

**SIZE:** 04/08 - 08/16 - 10/20 - 14/28 - 20/40 - 25/50

**DUMPING SIZE:**

**RX** = internal standard resistors  
**R4** = 400W external resistors (opt)  
**R8** = 800W external resistors (opt)

**PROTECTION:**  
**S** = Standard  
**T** = Tropicalized

**AXOR**  
adjustment  
identification  
number

**FEEDBACK:**  
**T0** = Tachogenerator (DC) (std)  
**A0** = Armature (opt)  
**E0** = Encoder (opt)  
**00** = No feedback  
(for **IO** and **PD** control mode) (opt)

**CONTROL MODE:**  
**RD** = Differential reference (std)  
**PD** = PWM + Direct (opt)  
**IO** = Demand current  
(torque mode) (opt)